



Status of anisotropic refinement in deal.II

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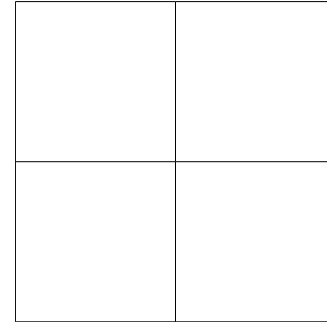
Anisotropic refinement: Motivation

- ▶ Resolution of anisotropic solution features like: shocks, shear layers, boundary layers, etc.
- ▶ Compressible flows: about 50% of all elements are located in the boundary layer

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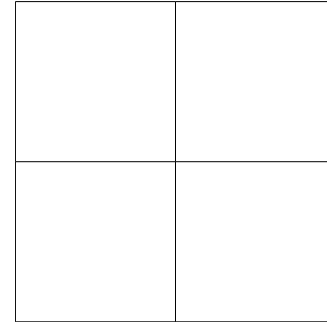
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Assume: wanted size of h_y at boundary: $h_y = 0.005$



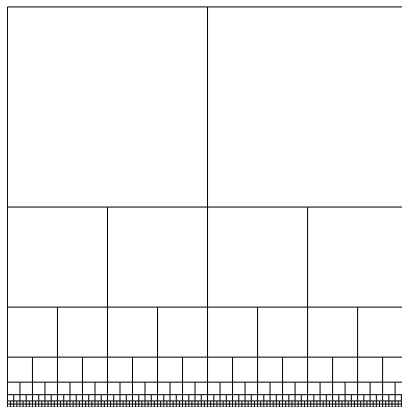
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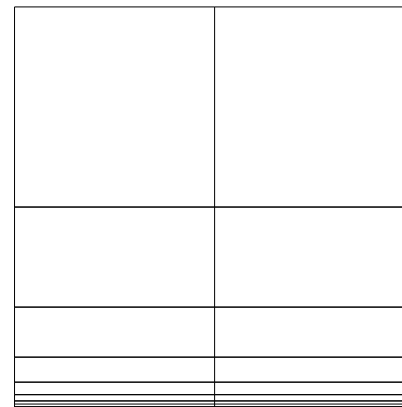
Assume: wanted size of h_y at boundary: $h_y = 0.005$

isotropic



766 cells

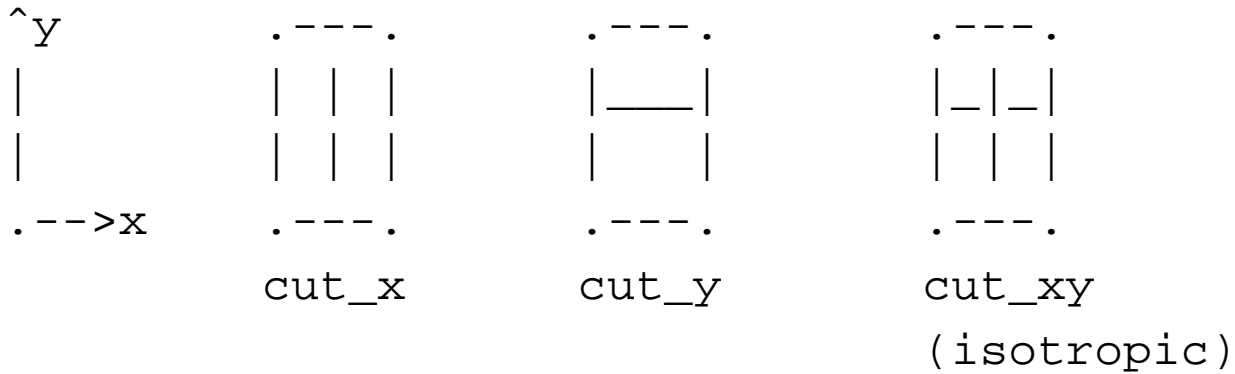
anisotropic



18 cells (aspect ratio: 128)

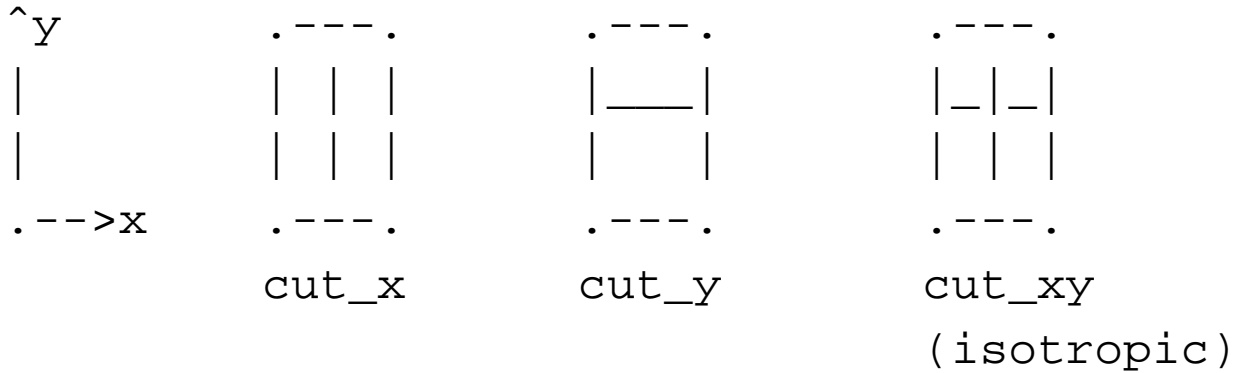
Typical aspect ratios in aerodynamics: $10^4 - 10^6$

Refinement cases in 2d



```
namespace RefineCase
{
    enum Type
    {
        no_refinement = 0,
        cut_x          = 1,
        cut_y          = 2,
        cut_xy         = 3
    };
}
```

Refinement cases in 2d



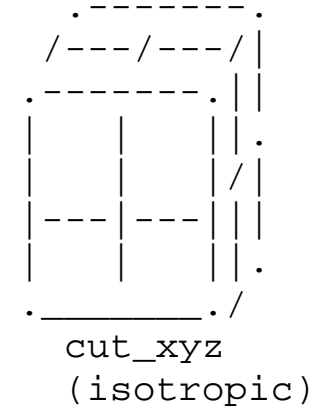
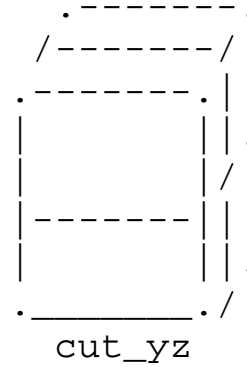
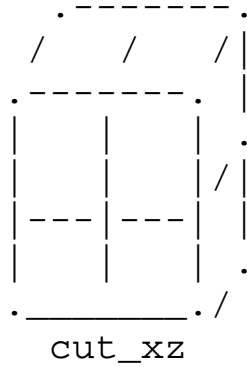
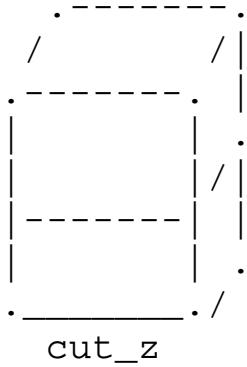
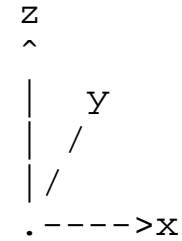
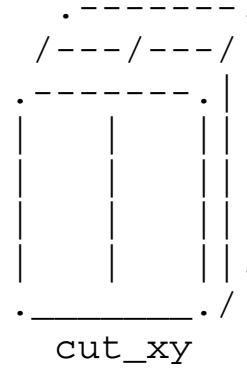
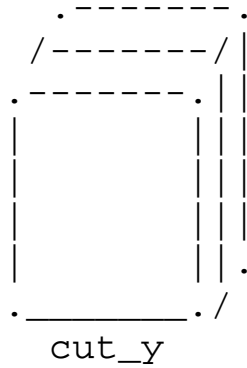
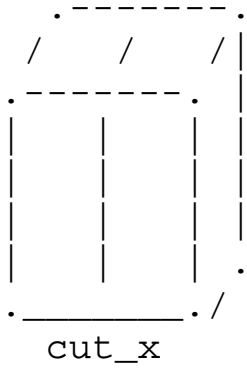
```
namespace RefineCase
```

```
{
  enum Type
  {
    no_refinement = 0,
    cut_x         = 1,
    cut_y         = 2,
    cut_xy        = 3
  };
}
```

Note, that e.g.

$$\text{cut_xy} == \text{cut_x} \mid \text{cut_y}$$

Refinement cases in 3d




```
namespace RefineCase
{
    enum Type
    {
        no_refinement = 0,
        cut_x         = 1,
        cut_y         = 2,
        cut_xy        = 3,
        cut_z         = 4,
        cut_xz        = 5,
        cut_yz        = 6,
        cut_xyz       = 7
    };
}
```

```
namespace RefineCase
```

```
{
```

```
    enum Type
```

```
    {
```

```
        no_refinement = 0,
```

```
        cut_x         = 1,
```

```
        cut_y         = 2,
```

```
        cut_xy        = 3,
```

```
        cut_z         = 4,
```

```
        cut_xz        = 5,
```

```
        cut_yz        = 6,
```

```
        cut_xyz       = 7
```

```
    };
```

```
}
```

note, that e.g.

```
cut_yz == cut_y | cut_z
```

```
cut_xyz == cut_yz | cut_x
```



Local refinement in deal.II

Isotropic refinement (current state):

```
cell->set_refine_flag();  
[....]  
tria.execute_coarsening_and_refinement();
```

Anisotropic refinement:

```
cell->set_refine_flag(RefineCase::cut_x);
```

Identical calls for isotropic refinement (for 2d):

```
cell->set_refine_flag(RefineCase::cut_xy);  
cell->set_refine_flag(GeometryInfo<dim>::isotropic_refinement);  
cell->set_refine_flag(); // backward compatibility!!!
```

Implementation:

```
template <int dim>  
class CellAccessor {  
public:  
    void set_refine_flag (RefineCase::Type ref_case=  
                        GeometryInfo<dim>::isotropic_refinement) const;  
};
```

Changes required in user codes

Incompatible changes:

- ▶ **Changes in `deal.II` which force user codes to be changed (e.g. to make them compile or to recover old functionality).**

Changes for new functionality:

- ▶ **Changes required in user code for gaining a new functionality (e.g. anisotropic refinement)**



Incompatible changes (1)

None, up to now! E.g. step-12 (isotropic refinement) runs without any change!

The interfaces of some internal functions have been extended. E.g.

```
template <int dim>
unsigned int
GeometryInfo<dim>::child_cell_on_face (const unsigned int face,
                                        const unsigned int subface,
                                        const bool face_orientation);
```

has been extended to

```
template <int dim>
unsigned int
GeometryInfo<dim>::child_cell_on_face (const RefineCase::Type ref_case,
                                        const unsigned int face,
                                        const unsigned int subface,
                                        const bool face_orientation);
```

However, this function should not be used in user codes anyway. The right function to be used is e.g. `cell->neighbor_child_on_subface(...)`.



DLR

Incompatible changes (2)

Variable names:

- ▶ `GeometryInfo<dim>::children_per_cell` **and**
- ▶ `GeometryInfo<dim>::subfaces_per_face`

Incompatible changes (2)

Variable names:

- ▶ `GeometryInfo<dim>::children_per_cell` **and**
- ▶ `GeometryInfo<dim>::subfaces_per_face`

Three possibilities:

- ▶ **keep them unchanged, or**
- ▶ **change them to** `GeometryInfo<dim>::max_children_per_cell` **and** `GeometryInfo<dim>::max_children_per_face` **(incompatible change!), or**
- ▶ **change them to the new names and keep the old ones for backward compatibilities (at least for a while)**

Changes required for new functionality (anisotropic ref.)

replace ...

GeometryInfo<dim>::children_per_cell

GeometryInfo<dim>::subfaces_per_face

by ...

cell->n_children()

face->n_children()

In the context of face integrals (FEFaceValues, FESubfaceValues)

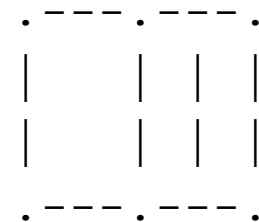
replace cell->neighbor(face_no)->has_children()

by cell->face(face_no)->has_children()

E.g. in step-12 (assemble_system2) only one line of code must be added

```
<         if (neighbor->level() == cell->level() &&
<             neighbor->index() > cell->index())
---
>         if ((neighbor->level() == cell->level() &&
>             neighbor->index() > cell->index()) ||
>             neighbor->level() > cell->level())
```

to include the case



Current implementation

Situation: cell (on level), neighboring cell n has children $c0$, $c1$ (on level+1).

Problem: faces of cell are on level, faces of $c0$ are on level+1,
 line l is on level and level+1 (!!)



Currently, faces in deal.II are stored in TriangulationLevel. Therefore, line l on level must be duplicated to be stored also on level+1.

Current implementation

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Currently, faces in deal.II are stored in TriangulationLevel. Therefore, line l on level must be duplicated to be stored also on level+1.

Problems of duplicated lines:

- ▶ **Multiple storage of (same) data on two (max. `n_levels()`) levels**
- ▶ **Restriction on refinement cases (see next slide)**

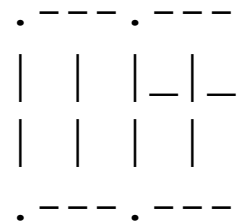
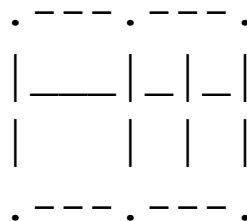
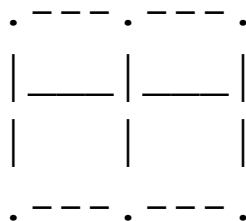
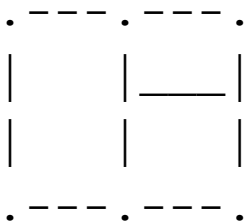
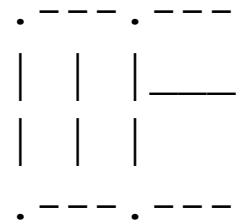
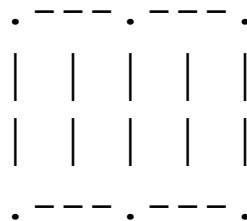
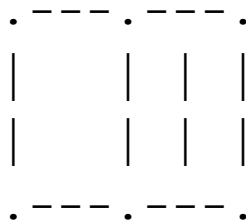
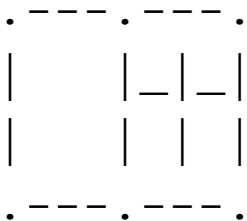
Therefore, association of faces with levels is a design flaw!

Duplicated faces: restriction of refinement cases

Refinement cases of two neighboring cells

Can be realized

Can NOT be realized

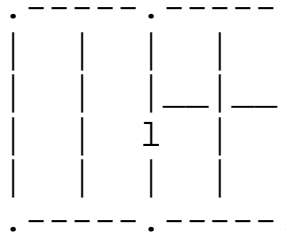
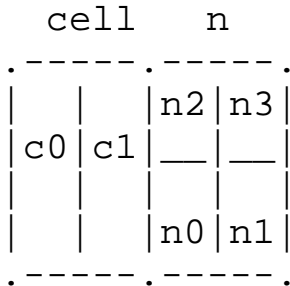


Problem of non-realizable refinement cases

Can not be realized:



Situation: cell (on level) with children c_0, c_1 ,
 neighboring cell n with children n_0, \dots, n_3 .
 cell and n on level, children on level+1.



Problem:

line $l = \text{cell} \rightarrow \text{line}(1)$ **on** level **with** $l \rightarrow \text{has_children}() = \text{true}$,
duplicate line $dl = c_1 \rightarrow \text{line}(1)$ **on** level+1,
BUT: $dl \rightarrow \text{has_children}() \neq \text{true}$



Change of internal data structures

Separate faces from `TriangulationLevel`.

- ▶ This change does not effect the current functionality or interface of `deal.II`
- ▶ This change allows anisotropic refinement without duplicate faces
- ▶ Removes restriction on refinement cases

Sketch of old internal data structure

```
TriangulationLevel<0> {...};

TriangulationLevel<1>: public TriangulationLevel<0> {
    LinesData lines;
    void reserve_space();
    ...
};

TriangulationLevel<2>: public TriangulationLevel<1> {
    QuadsData quads;
    void reserve_space();
    ...
};

TriangulationLevel<3>: public TriangulationLevel<2> {
    HexesData hexes;
    void reserve_space();
    ...
};

template <int dim>
class Triangulation {
private:
    std::vector<TriangulationLevel<dim>* > levels;
    ...
};
```

Sketch of new internal data structure

```
template<typename G>
class Objects {
    vector<G> cells;
    vector<bool> used;
    void reserve_space(); ... };

class ObjectsHex: public Objects<Hexahedron> {
    vector<bool> face_orientations; };

class TriangulationLevel<0> {...};           // unchanged
class TriangulationLevel<1>: public Objects<Line>,
                             public TriangulationLevel<0> {...};
class TriangulationLevel<2>: public Objects<Quad>,
                             public TriangulationLevel<0> {...};
class TriangulationLevel<3>: public ObjectsHex,
                             public TriangulationLevel<0> {...};

class TriangulationFaces<1> {};              // no data
class TriangulationFaces<2>: public Objects<Line> {...};
class TriangulationFaces<3>: public Objects<Quads> {...};

template <int dim>
class Triangulation {
private:
    std::vector<TriangulationLevel<dim>*> levels;
    TriangulationFaces<dim> faces;           // new!
};
```